

Solution Interfacing  
2013/2014



ANSWER BOOKLET

Student : .....	Number : .....		
Course : .....	Department : .....	Number : .....	
Division : .....	Instructor : .....		
Date : .....	Day	Month	Year

For Instructor's Use

Question	Grade
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<b>Total</b>	

Problem #1:

Type J TC is to be used in a measurement system that provide an output of 2V at 20°C. A solid state sensor will be used to provide reference temp. compensation. the sensor has 3 terminals: supply voltage  $V_s$ , output  $V_T$  and ground. The output varies  $8 \text{ mV}/^\circ\text{C}$ .

Solution:

J TC with  $0^\circ\text{C}$  reference its output  $10.78 \text{ mV}$  @  $20^\circ\text{C}$  from tables.

$$V_{J_0}(20^\circ\text{C}) = 10.8 \text{ mV}.$$

$$\text{overall gain} = \frac{2 \text{ V}}{10.8 \text{ mV}} = \underline{\underline{185.5}}$$

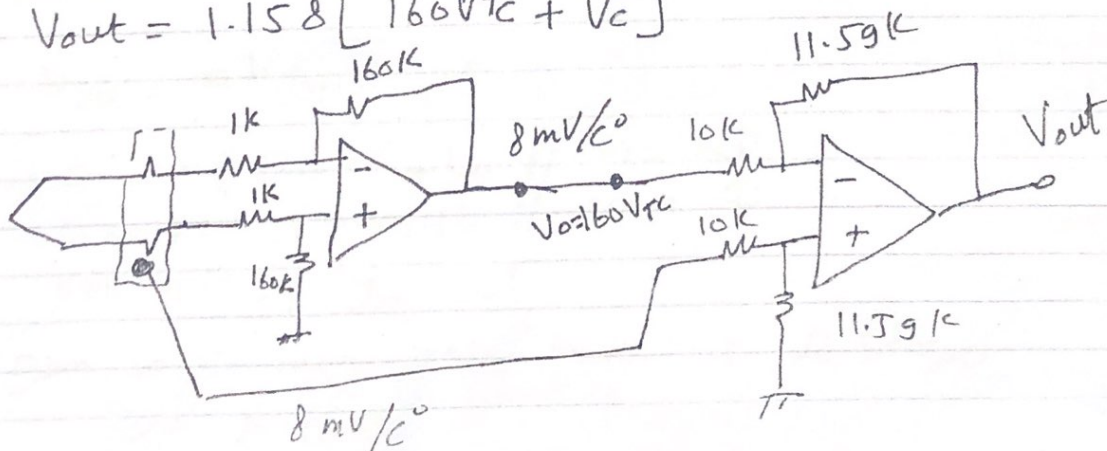
From tables of J TC slope is approx.  $50 \mu\text{V}/^\circ\text{C}$ .  
slope of sensor  $8 \text{ mV}/^\circ\text{C}$ .

$$\frac{8 \text{ mV}/^\circ\text{C}}{50 \mu\text{V}/^\circ\text{C}} = 160 \text{ times larger}$$

to make the rest of the gain

$$\frac{185.5}{160} = \underline{\underline{1.159}}$$

$$V_{out} = 1.158 [160 V_{TC} + V_c]$$



## Problem 2:

Temperature for a plating operation must be measured for control within a range of 500 - 600  $F^{\circ}$ . Develop measuring system that scales this temperature into 0 to 5V for an input to 8-bit ADC; measurement must be within  $\pm 1\%$ .

Solution:

Range: 260 - 315.6  $^{\circ}C$

Choosing the sensor: TC & RTD could fit to the problem

let us choose J TC with reference 25  $\pm 5^{\circ}C$  to satisfy the accuracy.

Correction circuit must be used to compensate the reference voltage.

From tables:

$$\text{For } 260^{\circ}C; V_{J_{25}}(260) = V_{J_0}(25) - V_{J_0}(25)$$

$$V_{J_{25}}(260) = 12.84 \text{ mV}$$

$$V_{J_{25}}(315.6) = 15.9 \text{ mV}$$

$$V_{ADC} = m V_{J_{25}} + V_0$$

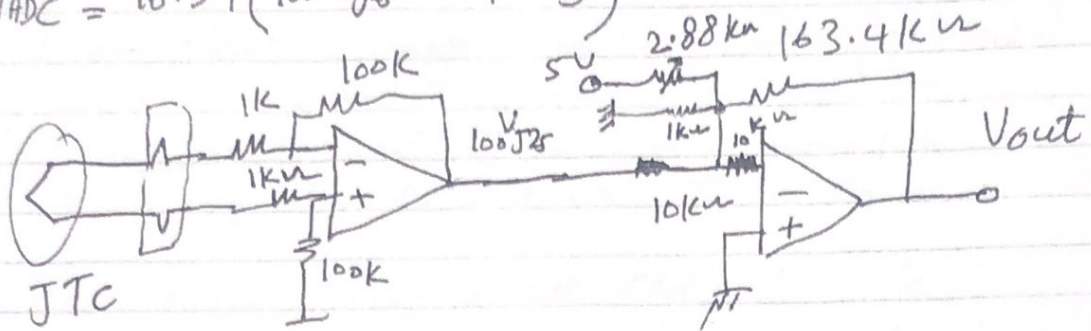
$$\begin{aligned} 0 &= m(12.8 \text{ mV}) + V_0 \\ 5 &= m(15.9 \text{ mV}) + V_0 \end{aligned} \quad \parallel \quad \begin{aligned} m &= 1634 \\ V_0 &= -21 \end{aligned}$$

$$V_{ADC} = 1634 V_{J_{25}} - 21$$

gain is so large, we make it 2 stages

$$100 \times 16.34$$

$$V_{ADC} = 16.34(100 V_{J25} - 1.29)$$



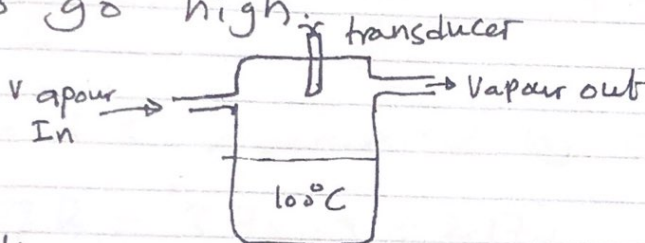


### Problem #3:

Vapour flows through chamber containing liquid at  $100^{\circ}\text{C}$ . Control system will regulate the Vapour temperature, so a measurement must be provided to convert  $50 - 80^{\circ}\text{C}$  into 0 to 2V.

the error should not exceed  $\pm 1^{\circ}\text{C}$ .

If the liquid level rises to the tip of the transducer, the temp. will suddenly rise to  $100^{\circ}\text{C}$ . The event should cause an alarm to go high.



### Solution:

selection of sensor RTD is the best choice.

Let us choose RTD with the following Spec.

$$R @ 65^{\circ}\text{C} = 150\Omega$$

$$\alpha = .004/^{\circ}\text{C}$$

$$P_D = 30\text{mW}/^{\circ}\text{C}$$

$$\textcircled{a} @ 50^{\circ}\text{C} \text{ RTD} = 150 [1 + .004 [50 - 65]] = 141\Omega$$

$$\textcircled{b} @ 80^{\circ}\text{C} \text{ RTD} = 159\Omega$$

$$\textcircled{c} @ 100^{\circ}\text{C} \text{ RTD} = 171\Omega$$

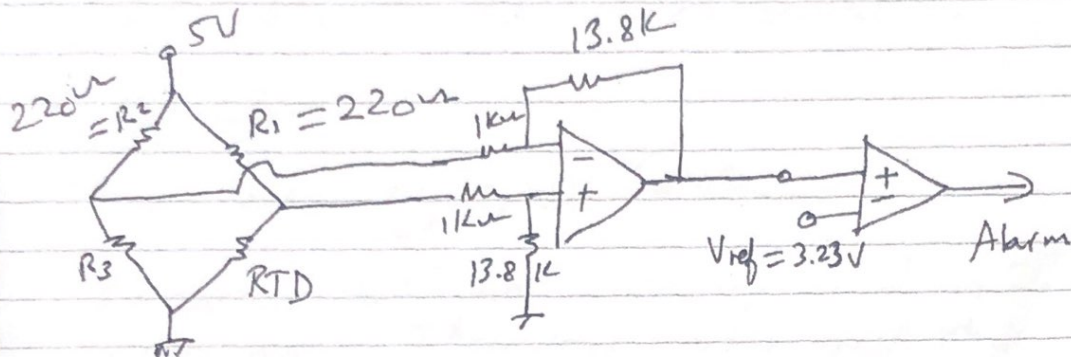
For  $1^{\circ}\text{C}$  error because of Self-heating we can find max. current

$$P = P_D \Delta T = 30\text{mW}/^{\circ}\text{C} \times 1^{\circ}\text{C} = 30\text{mW}$$

max. Current

$$I = \sqrt{\frac{P}{R}} = \sqrt{\frac{30}{159}} = 13.7 \text{ mA}$$

Bridge should be used for RTD



Value of  $R_1$  is determined by current  $< 13.7 \text{ mA}$

$$V = IR = 13.7 \times 159 = 2.17 \text{ V}$$

$$R_1 = (5 - 2.17) / 159 = 206.5 \Omega$$

Let us choose  $R_1 = 220 \Omega$

To null the bridge @  $50^\circ \text{C}$  we will make

$$R_2 = 220 \Omega \quad \& \quad R_3 = 141 \Omega$$

$$\text{@ } 50^\circ \text{C} \Rightarrow \Delta V = 5 \left( \frac{141}{220+141} - \frac{141}{220+141} \right) = 0$$

$$\text{@ } 80^\circ \text{C} \Rightarrow \Delta V = 5 \left( \frac{159}{220+159} - \frac{141}{220+141} \right) = .1447 \text{ V}$$

$$\text{@ } 100^\circ \text{C} \Rightarrow \Delta V = .2338 \text{ V}$$

$$\text{gain needed} = \frac{2}{.1447} = \underline{\underline{13.8}}$$

$$V_{\text{ref}} = 13.8 \times .2338 = 3.23 \text{ V}$$

### Problem # 4:

Develop a system that turns on alarm LED when the temperature in a chamber reaches  $10 \pm 0.5^\circ\text{C}$ . When the temperature drops below  $8^\circ\text{C}$  the LED should be turned off.

### Solution:

it looks hysteresis Comparator

because we are interested just in 2 temperatures Thermistor is the best choice.

we choose thermistor;  $P_D = 5\text{mW}/^\circ\text{C}$ .

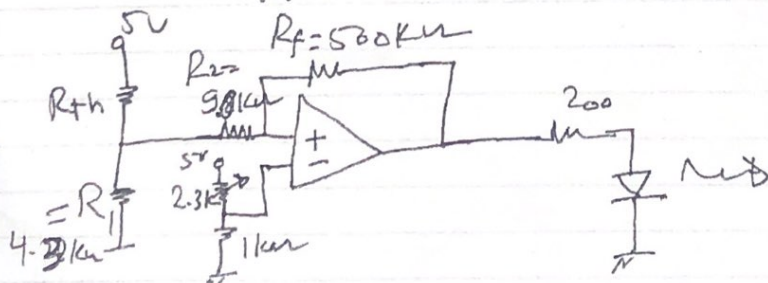
$$R_{th}|_{10^\circ\text{C}} = 10\text{k}\Omega; R_{th}|_{8^\circ\text{C}} = 11\text{k}\Omega$$

$\pm 0.5^\circ\text{C}$  requirement means that self heating must be kept below  $\pm 0.5^\circ\text{C}$ .

to be sure let us use  $0.25^\circ\text{C}$ .

$$P = P_D \cdot \Delta T = 5\text{mW}/^\circ\text{C} \times 0.25^\circ\text{C} = 1.25\text{mW}$$

$$I = \sqrt{\frac{1.25\text{mW}}{10\text{k}\Omega}} = 0.354\text{mA}$$



$$V_{Th} = I R_1 = 0.35\text{mA} \times 10\text{k}\Omega = 3.5\text{V}$$

$$R_1 = \frac{5 - 3.5}{0.35} = 4.28\text{k}\Omega \text{ we will use } 4.3\text{k}\Omega$$



For  $10^{\circ}\text{C}$  ;  $V_D = 1.5\text{V}$

"  $8^{\circ}\text{C}$  ;  $V_D = 1.41\text{V}$

difference is  $.09\text{V}$  required for hysteresis

Hysteresis  $\left\{ \frac{R_2}{R_f} \times 5 = .09 \Rightarrow \frac{R_2}{R_f} = .018 \right.$

choose  $R_f = 50\text{k}\Omega$  ;  $\Rightarrow R_2 = 9\text{k}\Omega$

Note: Schmitt trigger

